

STA 4321 REVIEW (Chapters 1 - 5)

1 Probability (Chapter 1)

1.2 Sample Spaces

- Experiment: any process of data collection or observations where the outcomes are subject to variation.
 - ex1) toss a coin three times.
 - ex2) observe # of jobs in a print queue of a mainframe computer.
 - ex3) observe the length of time between successive earthquakes in L.A.
- Sample space (Ω): the set of all possible outcomes
 - ex1) $\Omega = \{HHH, HHT, HTH, THH, HTT, THT, TTH, TTT\}$.
 - ex2) $\Omega = \{0, 1, 2, 3, \dots\}$.
 - ex3) $\Omega = \{t \in \mathcal{R} | t \geq 0\}$.
- Event: subset of Ω .
 - ex1) the first coin is Head, $A = \{HHH, HHT, HTH, HTT\}$.
 - ex2) fewer than five jobs, $A = \{0, 1, 2, 3, 4\}$.
 - ex3) the length of time is less than 10 seconds, $A = \{0 \leq t < 10\}$.
- Event relation
 - (i) Union: $C = A \cup B$, either A occurs or B occurs or both occur.
 - (ii) Intersection: $C = A \cap B$, both A and B occur.
 - (iii) Complement: A^c , A does not occur.
 - (iv) Disjoint: $A \cap B = \phi$.
- Laws of set theory
 - (i) Commutative laws: $A \cup B = B \cup A$, $A \cap B = B \cap A$.
 - (ii) Associative laws: $(A \cup B) \cup C = A \cup (B \cup C)$,
 $(A \cap B) \cap C = A \cap (B \cap C)$.
 - (iii) Distributive laws: $(A \cup B) \cap C = (A \cap C) \cup (B \cap C)$,
 $(A \cap B) \cup C = (A \cup C) \cap (B \cup C)$.

1.3 Probability Measures

- $P : \Omega \rightarrow \mathcal{R}$ satisfies
 - (i) $P(\Omega) = 1$,

- (ii) $0 \leq P(A) \leq 1$ for any $A \subset \Omega$,
- (iii) $A_1 \cap A_2 = \phi \Rightarrow P(A_1 \cup A_2) = P(A_1) + P(A_2)$.
More generally, if $A_1, A_2, \dots, A_n, \dots$ are mutually disjoint, then

$$P\left(\bigcup_{i=1}^{\infty} A_i\right) = \sum_{i=1}^{\infty} P(A_i).$$

By three properties above,

P1. $P(A^c) = 1 - P(A)$

P2. $P(\phi) = 0$

P3. If $A \subset B$, then $P(A) \leq P(B)$

P4. $P(A \cup B) = P(A) + P(B) - P(A \cap B)$

1.4 Computing Probabilities: counting methods

- Uniform model: all the outcomes are equally likely.

$$P(A) = \frac{\# \text{ of ways } A \text{ can occur}}{\text{total } \# \text{ of outcomes}}$$

- More complex situations

- (i) Multiplication principle

exp't 1: m outcomes, exp't 2: n outcomes $\Rightarrow mn$ outcomes

exp't 1: n_1 , exp't 2: n_2 , exp't p: $n_p \Rightarrow n_1 n_2 \cdots n_p$ outcomes

- (ii) Sampling without replacement and with replacement

For a set of size n and a sample size r ,

of different ordered samples with replacement: n^r ,

without replacement: $n(n-1) \cdots (n-r+1)$,

(if $n = r$, $n(n-1) \cdots 1 = n!$.)

- (iii) Binomial coefficients

$\binom{n}{r}$: # of unordered samples without replacement

$$(a+b)^n = \sum_{k=0}^n \binom{n}{k} a^k b^{n-k}$$

In particular, $2^n = \sum_{k=0}^n \binom{n}{k}$.

- (iv) Multinomial coefficients

$$\binom{n}{n_1 n_2 \cdots n_r} = \frac{n!}{n_1! n_2! \cdots n_r!}$$

: # of ways that n objects can be grouped into r classes with n_i in the i th class, $i = 1, \dots, r$ and $\sum_{i=1}^r n_i = n$.

$$(x_1 + x_2 + \cdots + x_r)^n = \sum \binom{n}{n_1 n_2 \cdots n_r} x_1^{n_1} x_2^{n_2} \cdots x_r^{n_r}$$

1.5 Conditional Probability

- Conditional probability

$$P(A|B) = \frac{P(A \cap B)}{P(B)}, \quad P(B) \neq 0.$$

: conditional probability of A given B.

- Multiplication law

$$P(A \cap B) = P(A|B)P(B), \quad P(B) \neq 0.$$

- Law of total probability

Let B_1, B_2, \dots, B_n be such that $\bigcup_{i=1}^n B_i = \Omega$ and $B_i \cap B_j = \emptyset$ for $i \neq j$, with $P(B_i) > 0$ for all i . Then, for any A ,

$$P(A) = \sum_{i=1}^n P(A|B_i)P(B_i).$$

- Bayes rule

Let A and B_1, B_2, \dots, B_n be events where the $\bigcup_{i=1}^n B_i = \Omega$ and $B_i \cap B_j = \emptyset$ for $i \neq j$, with $P(B_i) > 0$ for all i . Then,

$$P(B_j|A) = \frac{P(A|B_j)P(B_j)}{\sum_{i=1}^n P(A|B_i)P(B_i)}.$$

1.6 Independence

A and B are independent events $\iff P(A \cap B) = P(A)P(B)$.
mutually independent: $P(A_1 \cap \dots \cap A_m) = P(A_1) \dots P(A_m)$.

2 Random Variables (Chapter 2)

random variable (r.v.): a function from Ω to \mathcal{R} .

2.1 Discrete Random Variables

- Frequency function (probability mass function)

$$p(x_i) = P(X = x_i), \quad \sum p(x_i) = 1.$$

- Cumulative distribution function (cdf)

$$F(x) = P(X \leq x), \quad -\infty < x < \infty.$$

: non-decreasing and

$$\lim_{x \rightarrow -\infty} F(x) = 0, \quad \lim_{x \rightarrow \infty} F(x) = 1.$$

- Bernoulli: Success or Failure

X : 0 or 1

See the table.

- Binomial: n independent Bernoulli experiments

X : total number of successes $\sim B(n, p)$.

See the table.

- Bernoulli and Binomial

X_1, X_2, \dots, X_n : independent Bernoulli r.v. with $P(X_i = 1) = p$.

$$\implies Y = X_1 + X_2 + \dots + X_n \sim B(n, p).$$

- Geometric

X : under Bernoulli trials, # of trials up to and including the first success.

See the table.

- Negative Binomial

X : under Bernoulli trials, # of trials until r successes in all $\sim NB(r, p)$.

See the table.

- Geometric and Negative Binomial

X_1, X_2, \dots, X_r : independent Geometric r.v. with p .

$$\implies Y = X_1 + X_2 + \dots + X_r \sim NB(r, p).$$

- Hypergeometric

Suppose an urn contains n balls, of which r are black and $n - r$ are white.

X : # of black balls drawn when taking m balls without replacement $\sim H(m; r, n)$.

See the table.

- Poisson

X : # of times some event occurs in a given interval of time $\sim Poisson(\lambda)$.

See the table.

- Binomial and Poisson

- Setting: dividing an interval into a very large number of small subintervals of equal length.
- Assumptions (of Poisson):
 - (i) independent increment: what happens in one subinterval is independent of what happens in any other subinterval.
 - (ii) stationarity: the probability of an event is the same in each subinterval.
 - (iii) proportionality: the probability of an event is proportional to the length of the subinterval.
 - (iv) rareness: events do not happen simultaneously.

Binomial with large n and small $p \longrightarrow \text{Poisson}(\lambda)$ where $np \rightarrow \lambda$.

2.2 Continuous Random Variables

- Density function $f(x)$
 - (i) $f(x) \geq 0$
 - (ii) $\int_{-\infty}^{\infty} f(x)dx = 1$
 - (iii) $P(a < X < b) = \int_a^b f(x)dx, \quad a < b.$
- Cdf and density function

$$f(x) = \frac{dF(x)}{dx}$$

- Uniform $[0, 1] \sim U[0, 1]$

See the table.

- Exponential $\sim \text{Exp}(\lambda)$

X : waiting time

See the table.

memoryless property – $P(T > t + s | T > s) = P(T > t)$

: the probability that the unit will last t more time units does not depend on s .

- Gamma $\sim \text{Gamma}(\alpha, \lambda)$

$$\Gamma(\alpha) = \int_0^{\infty} u^{\alpha-1} e^{-u} du,$$

$\Gamma(\alpha) = (\alpha - 1)!$ if α is a natural number.

See the table.

- Exponential and Gamma

X_1, X_2, \dots, X_n : independent Exponential r.v. with λ .

$\implies Y = X_1 + X_2 + \dots + X_n \sim \text{Gamma}(n, \lambda).$

- Poisson, Exponential and Gamma
 - distribution of # of arrivals during $[0, t] \sim \text{Poisson}(\lambda t)$
 - distribution of waiting time until the first arrival $\sim \text{Exp}(\lambda)$
 - distribution of waiting time until the r th arrival $\sim \text{Gamma}(r, \lambda)$
- Normal $\sim N(\mu, \sigma^2)$
See the table.
 Standard normal $\sim N(0, 1)$.
- Central Limit Theorem (CLT): if a r.v. is the sum of a large number of independent r.v.'s, it is approximately normally distributed.
- If $X \sim N(\mu, \sigma^2)$ and $Y = aX + b$, then $Y \sim N(a\mu + b, a^2\sigma^2)$.

2.3 Functions of a Random Variable

- X : continuous r.v. with density f_X .
 $Y = g(X)$, g : differentiable, strictly monotonic on some interval I .
 $f(x) = 0$ if x is not in I .
 $\implies Y$ has the density function

$$f_Y(y) = f_X(g^{-1}(y)) \left| \frac{d}{dy} g^{-1}(y) \right|,$$

for y such that $y = g(x)$ for some x , and $f_Y(y) = 0$ if $y \neq g(x)$ for any x in I . Here g^{-1} is the inverse function of g .

- F : cdf of X and $Z = F(X)$, then Z has a uniform distribution on $[0, 1]$.
- $U \sim U[0, 1]$ and $X = F^{-1}(U)$. Then, the cdf of X is F .

3 Joint Distribution (Chapter 3)

If X_1, X_2, \dots, X_n are jointly distributed r.v.'s, their joint cdf is

$$F(x_1, x_2, \dots, x_n) = P(X_1 \leq x_1, X_2 \leq x_2, \dots, X_n \leq x_n)$$

3.2 Discrete Random Variables

- Joint frequency function (joint probability mass function)

$$p(x_i, y_j) = P(X = x_i, Y = y_j)$$

- Marginal frequency function

$$p_X(x) = \sum_j p(x, y_j)$$

$$p_Y(y) = \sum_i p(x_i, y)$$

- X_1, \dots, X_m : discrete r.v.'s

$$p(x_1, \dots, x_m) = P(X_1 = x_1, \dots, X_m = x_m)$$

3.3 Continuous Random Variables

- Joint cdf: $F(x, y)$

- Joint density function: $f(x, y) = \frac{\partial^2}{\partial x \partial y} F(x, y)$

- Marginal density function

$$f_X(x) = \int f(x, y) dy$$

$$f_Y(y) = \int f(x, y) dx$$

- $P((X, Y) \in A) = \int \int_A f(x, y) dy dx$

- Bivariate normal

$$f(x, y) = \frac{1}{2\pi\sigma_X\sigma_Y\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)}\left[\frac{(x-\mu_X)^2}{\sigma_X^2} + \frac{(y-\mu_Y)^2}{\sigma_Y^2} - \frac{2\rho(x-\mu_X)(y-\mu_Y)}{\sigma_X\sigma_Y}\right]\right)$$

$$-\infty < \mu_X, \mu_Y < \infty, \sigma_X, \sigma_Y > 0, -1 < \rho < 1$$

marginal distribution: $X \sim N(\mu_X, \sigma_X^2)$ and $Y \sim N(\mu_Y, \sigma_Y^2)$

3.4 Independent Random Variables

- X_1, X_2, \dots, X_n : independent

$$\iff F(x_1, x_2, \dots, x_n) = F_{X_1}(x_1)F_{X_2}(x_2) \cdots F_{X_n}(x_n)$$

$$\iff f(x_1, x_2, \dots, x_n) = f_{X_1}(x_1)f_{X_2}(x_2) \cdots f_{X_n}(x_n)$$

$$\iff P(X_1 \in A_1, X_2 \in A_2, \dots, X_n \in A_n) \\ = P(X_1 \in A_1)P(X_2 \in A_2) \cdots P(X_n \in A_n)$$

for all x_1, x_2, \dots, x_n and A_1, A_2, \dots, A_n .

3.5 Conditional Distribution

– Discrete case

$$\begin{aligned}
 P(X = x_i | Y = y_j) &= \frac{P(X = x_i, Y = y_j)}{P(Y = y_j)} \\
 &= \frac{p_{XY}(x_i, y_j)}{p_Y(y_j)} \quad \text{if } p_Y(y_j) > 0 \\
 p_{XY}(x, y) &= p_{X|Y}(x|y)p_Y(y) \\
 p_X(x) &= \sum_y p_{X|Y}(x|y)p_Y(y)
 \end{aligned}$$

– Continuous case

$$\begin{aligned}
 f_{Y|X}(y|x) &= \frac{f_{XY}(x, y)}{f_X(x)} \quad \text{if } f_X(x) > 0 \\
 f_{XY}(x, y) &= f_{Y|X}(y|x)f_X(x) \\
 f_Y(y) &= \int f_{Y|X}(y|x)f_X(x)dx
 \end{aligned}$$

Bivariate normal:

$$Y|X = x \sim N(\mu_Y + \rho(x - \mu_X)\sigma_Y/\sigma_X, \sigma_Y^2(1 - \rho^2))$$

3.6 Functions of Jointly Distributed Random Variables

– Sums: $Z = X + Y$ (convolution)

$$\begin{aligned}
 p_Z(z) &= \sum_x p(x, z - x) \\
 &= \sum_x p_X(x)p_Y(z - x) \quad \text{if } X \& Y : \text{ independent} \\
 f_Z(z) &= \int f(x, z - x)dx \\
 &= \int f_X(x)f_Y(z - x)dx \quad \text{if } X \& Y : \text{ independent}
 \end{aligned}$$

– General case: change of variables (see p.95)

3.7 Functions of Jointly Distributed Random Variables

$X_1, X_2, \dots, X_n \sim$ cdf F and density f (i.i.d.)

– $U = \max_i X_i, V = \min_i X_i$

$$\begin{aligned}
 F_U(u) &= [F(u)]^n, & f_U(u) &= nf(u)[F(u)]^{n-1} \\
 F_V(v) &= 1 - [1 - F(v)]^n, & f_V(v) &= nf(v)[1 - F(v)]^{n-1}
 \end{aligned}$$

– Order statistic: $X_{(1)} < X_{(2)} < \dots < X_{(n)}$

The density of $X_{(k)}$, the k th order statistic:

$$f_k(x) = \frac{n!}{(k-1)!(n-k)!} f(x)F^{k-1}(x)[1-F(x)]^{n-k}$$

4 Expected Values (Chapter 4)

4.1 Expected Value of a Random Variable : measure of center

- Discrete r.v. with frequency function $p(x)$

$$E(X) = \sum_i x_i p(x_i)$$

provided that $\sum_i |x_i| p(x_i) < \infty$. If the sum diverges, the expectation is undefined.

- Continuous r.v. with density function $f(x)$

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx$$

provided that $\int |x| f(x) dx < \infty$. If the integral diverges, the expectation is undefined.

4.1.1 Expectations of Functions of Random Variables

- THEOREM A

$$Y = g(X).$$

- (a) X : discrete with frequency function $p(x)$

$$\implies E(Y) = \sum_x g(x) p(x)$$

provided that $\sum |g(x)| p(x) < \infty$.

- (b) X : continuous with density function $f(x)$

$$\implies E(Y) = \int_{-\infty}^{\infty} g(x) f(x) dx$$

provided that $\int |g(x)| f(x) dx < \infty$.

- THEOREM B

$$Y = g(X_1, \dots, X_n).$$

- (a) X_i : discrete with joint frequency function $p(x_1, \dots, x_n)$

$$\implies E(Y) = \sum_{x_1, \dots, x_n} g(x_1, \dots, x_n) p(x_1, \dots, x_n)$$

provided that $\sum_{x_1, \dots, x_n} |g(x_1, \dots, x_n)| p(x_1, \dots, x_n) < \infty$.

- (b) X : continuous with joint density function $f(x_1, \dots, x_n)$

$$\implies E(Y) = \int \dots \int g(x_1, \dots, x_n) f(x_1, \dots, x_n) dx_1 \dots dx_n$$

provided that the integral with $|g|$ in place of g converges.

- COROLLARY A

X, Y : independent r.v.'s

g, h : fixed functions

$$\implies E[g(X)h(Y)] = E[g(X)]E[h(Y)]$$

4.2 Variance and Standard Deviation : measure of spreadness

- X : r.v. with $E(X)$

$$Var(X) = E[(X - E(X))^2]$$

provided that the expectation exist. The standard deviation of X is the square root of the variance.

$$\begin{aligned} Var(X) &= \sum_i (x_i - E(X))^2 p(x_i) \quad (\text{discrete}) \\ &= \int_{-\infty}^{\infty} (x - E(X))^2 f(x) dx \quad (\text{continuous}) \end{aligned}$$

- THEOREM A

$Var(X)$ exists and $Y = a + bX$.

$$\begin{aligned} Var(Y) &= b^2 Var(X) \\ \sigma_Y &= |b| \sigma_X \end{aligned}$$

- THEOREM B

$Var(X)$ exists.

$$Var(X) = E(X^2) - [E(X)]^2$$

- THEOREM C (Chebyshev's Inequality)

X : r.v. with mean μ and variance σ^2 . Then, for any $t > 0$,

$$P(|X - \mu| > t) \leq \frac{\sigma^2}{t^2}$$

- COROLLARY A

If $Var(X) = 0$, then $P(X = \mu) = 1$.

- MSE (Mean Squared Error)

$$\begin{aligned} MSE &= E[(X - x_0)^2] \\ &= Var(X) + [E(X - x_0)]^2 \\ &= \sigma^2 + \beta^2 \end{aligned}$$

4.3 Covariance and Correlation

- X & Y : jointly distributed r.v.'s with μ_X and μ_Y respectively.

$$Cov(X, Y) = E[(X - \mu_X)(Y - \mu_Y)]$$

provided that the expectation exists.

- THEOREM A

$U = a + \sum_{i=1}^n b_i X_i$ and $V = c + \sum_{j=1}^m d_j Y_j$

$$Cov(U, V) = \sum_{i=1}^n \sum_{j=1}^m b_i d_j Cov(X_i, Y_j)$$

– COROLLARY A

$$\text{Var}\left(a + \sum_{i=1}^n b_i X_i\right) = \sum_{i=1}^n \sum_{j=1}^m b_i b_j \text{Cov}(X_i, X_j)$$

– COROLLARY B

$$\text{Var}\left(\sum_{i=1}^n X_i\right) = \sum_{i=1}^n \text{Var}(X_i),$$

if the X_i are independent.

– Correlation coefficient

X & Y : jointly distributed r.v.'s, variances and covariances exist, and the variances are nonzero.

$$\rho = \frac{\text{Cov}(X, Y)}{\sqrt{\text{Var}(X)\text{Var}(Y)}}$$

– THEOREM B

$-1 \leq \rho \leq 1$. Furthermore, $\rho = \pm 1 \iff P(Y = a + bX) = 1$ for some a and b .

4.4 Conditional Expectation and Prediction

– Definitions and Examples

* Conditional expectation of Y given $X = x$

$$\begin{aligned} E(Y|X = x) &= \sum_y y p_{Y|X}(y|x) \quad (\text{discrete}) \\ &= \int y f_{Y|X}(y|x) dy \quad (\text{continuous}) \end{aligned}$$

More generally,

$$E[h(Y)|X = x] = \int h(y) f_{Y|X}(y|x) dy$$

* Law of total expectation: $E(Y) = E[E(Y|X)]$

* $\text{Var}(Y) = \text{Var}[E(Y|X)] + E[\text{Var}(Y|X)]$

– Prediction

Predicting Y by some function $h(X)$ in order to minimize MSE.

$$\begin{aligned} E[(Y - h(X))^2] &= E[E[(Y - h(X))^2|X]] \\ h(X) &= E[Y|X] \end{aligned}$$

4.5 Moment Generating Function (mgf)

$$\begin{aligned} M(t) &= E(e^{tx}) \\ &= \sum_x e^{tx} p(x) \quad (\text{discrete}) \\ &= \int_{-\infty}^{\infty} e^{tx} f(x) dx \quad (\text{continuous}) \end{aligned}$$

– PROPERTY A

If the mgf exists for t in an open interval containing zero, it uniquely determines the probability distribution.

– PROPERTY B

If the mgf exists for t in an open interval containing zero,

$$M^{(r)}(0) = E(X^r)$$

– PROPERTY C

If X has the mgf $M_X(t)$ and $Y = a + bX$, then Y has the mgf

$$M_Y(t) = e^{at} M_X(bt)$$

– PROPERTY D

X & Y : independent with M_X and M_Y , and $Z = X + Y$.

$$\implies M_Z(t) = M_X(t)M_Y(t)$$

on the common interval where both mgf's exist.

– Property D-1

X_1, X_2, \dots, X_n : independent

$$\iff M_{X_1, X_2, \dots, X_n}(t_1, t_2, \dots, t_n) = M_{X_1}(t_1)M_{X_2}(t_2) \cdots M_{X_n}(t_n).$$

4.6 Approximate Methods

– Propagation error (δ method)

$$Y = g(X) \approx g(\mu_X) + (X - \mu_X)g'(\mu_X) : \text{first order}$$

$$\mu_Y \approx g(\mu_X)$$

$$\sigma_Y^2 \approx \sigma_X^2 [g'(\mu_X)]^2$$

$$Y = g(X) \approx g(\mu_X) + (X - \mu_X)g'(\mu_X) + \frac{1}{2}(X - \mu_X)^2 g''(\mu_X) : \text{second order}$$

$$\mu_Y \approx g(\mu_X) + \frac{1}{2}\sigma_X^2 g''(\mu_X)$$

5 Limit Theorems (Chapter 5)

– Law of Large Numbers

$X_1, X_2, \dots, X_i, \dots$: a sequence of indep. r.v.'s, $E(X_i) = \mu$ & $Var(X_i) = \sigma^2$.

$$\bar{X}_n = \frac{1}{n} \sum_{i=1}^n X_i$$

Then, for any $\epsilon > 0$,

$$P(|\bar{X}_n - \mu| > \epsilon) \longrightarrow 0 \quad \text{as } n \rightarrow \infty$$

: convergence in probability

– Converge almost surely to α
 : if for every $\epsilon > 0$, $|Z_n - \alpha| > \epsilon$ only a finite number of times.

– Convergence in distribution

X_1, X_2, \dots : a sequence of r.v.'s with cdf F_1, F_2, \dots

X : a r.v.'s with cdf F .

X_n converges in distribution to X if

$$\lim_{n \rightarrow \infty} F_n(x) = F(x)$$

at every point at which is continuous.

– CONTINUITY THEOREM

F_n : a sequence of cdfs with corresponding mgf M_n .

F : a cdf with the mgf M .

$M_n(t) \rightarrow M(t)$ for all t in an open interval containing zero.

$$\implies F_n(x) \rightarrow F(x)$$

at all continuity points of F .

– CENTRAL LIMIT THEOREM (CLT)

X_1, X_2, \dots : a sequence of independent r.v.'s with mean 0 and variance σ^2 ,
 the cdf F and the mgf M defined in a neighborhood of zero.

$$S_n = \sum_{i=1}^n X_i$$

$$\implies \lim_{n \rightarrow \infty} P\left(\frac{S_n}{\sigma\sqrt{n}} \leq x\right) = \Phi(x), \quad -\infty < x < \infty$$

where $\Phi(\cdot)$ is the standard normal cdf.